Defence Seminar	
Seminar Title	: Design of False Data Injection Attacks and Their Detection and Mitigation in a Cyber-Physical System
Speaker	: Sushree Padhan (Rollno: 519cs1007)
Supervisor	: Ashok Kumar Turuk
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Abstract	Cyber-physical systems (CPSs) are susceptible to various attacks, of which false data injection (FDI) attacks are more critical. An attacker can launch an FDI attack at any chosen location in a CPS and modify the cyber and physical system&rayous data, causing errors in the system&rayous proper functioning. It is important to analyze FDI attacks at possible vulnerable locations and detect and mitigate them to defend the CPS. This thesis is an attempt in this direction. The thesis proposes strategies to design, detect, and mitigate FDI attacks in CPSs. A steady-state Kahman filter is used in the design of FDI attacks. Seven types of FDI attacks are proposed, in which each attack sequence follows a non-zero mean and zero-mean Gaussian distribution based on Kullback-Leibler (KL) divergence. It is observed that FDI attacks, in which the attacker simultaneously modifies the sensor measurements, actuator inputs, and physical system&rsquos state, generate maximum state estimation error. Next, a defense strategy is proposed for detecting and mitigating the non-zero mean and zero-mean Gaussian FDI attacks that simultaneously compromise the physical system, sensor measurements, and actuator inputs under a steady-state Kahman filter. A watermarking scheme is used to aid a Chi-square detector for attack detection. An attack mitigation scheme is proposed using control input synthesis and operating region concept. In this defense strategy, once an attack gets detected, the control inputs are generated from the proposed control input generation algorithm, where the system&rsquos operating regions are considering a time-varying Kahman filter, the non-zero mean and zero-mean Gaussian FDI attacks is proposed. In the first stage of the defense strategy, the watermarking technique aids a Chi-square detector for attack detection for attack detection. In the strateger of the defense strategy, a control scheme and a time-varying comperosises the physical system, sensor measurements, and actuator inputs. Then, a two-stage defense strat